

# SharkFest '18 Europe



### To send or not to send?..

How TCP Congestion Control algorithms work

### Vladimir Gerasimov

Packettrain.NET

## About me



- In IT since 2005
- Working for Unitop (integration, distribution)
- Where to find me:
  - Twitter: @Packet\_vlad
  - Q&A: <u>https://ask.wireshark.org</u>
  - Blog: packettrain.net
  - Social group <u>https://vk.com/packettrain</u> (Russian)





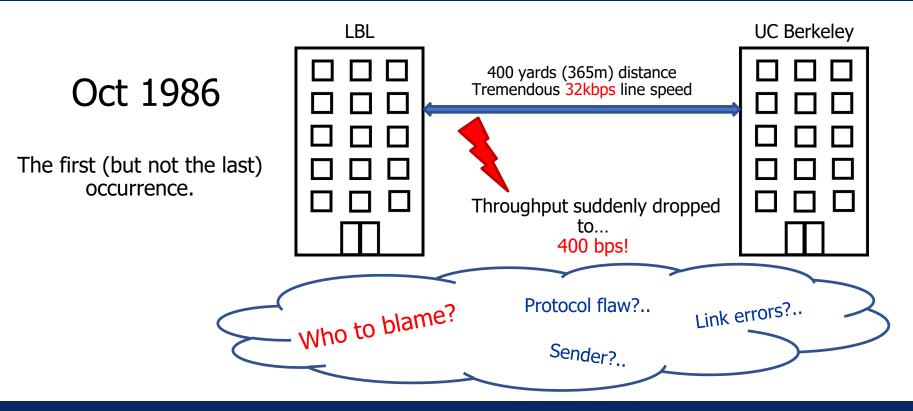
### http://files.packettrain.net:8001/SF18/

Login = password = sf18eu

(caution: size!!)

## The beginning.





## Let's capture!

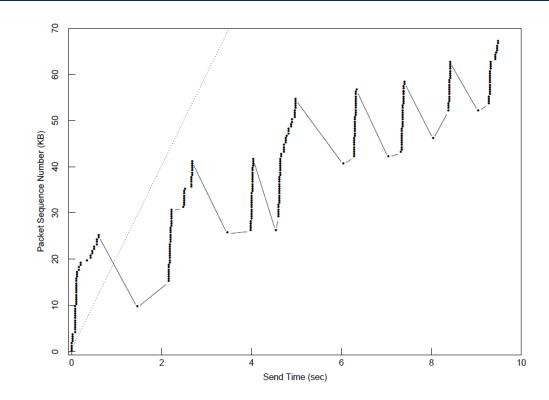


What was on the wire?

The sender (4.2 BSD) floods the link with tons of unnecessary retransmissions.

\* because it sends on own full rate and have inaccurate RTO timer

\* some chunks were retransmitted 5+ times!



## Congestion collapse

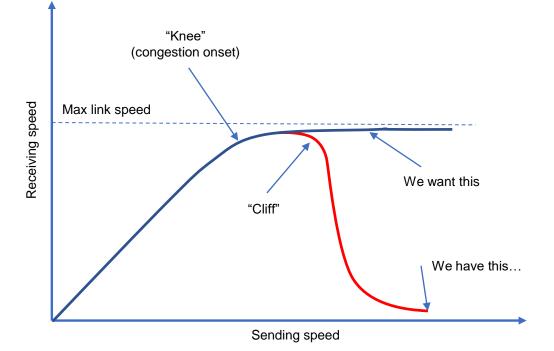


This is called "congestion collapse" – when goodput decreases by huge factor – up to 1000x!

[Fact: it was predicted by Nagle in 1984 before it occured in real life]

- Bad news: it NEVER disappears without countermeasures.

- So a sender has to slow down its rate ... or we just add more buffer to router?



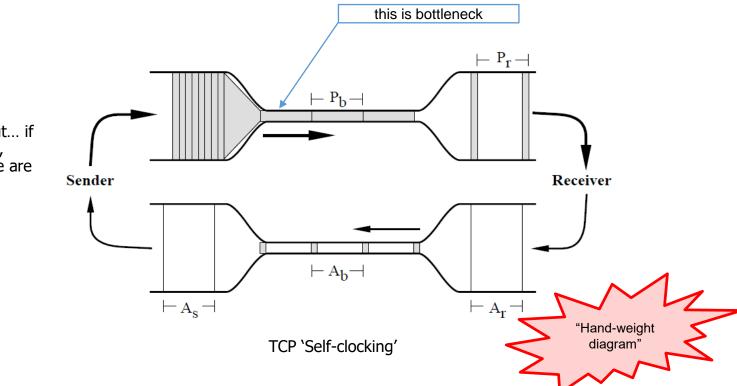
## Large buffers?



- Let's never drop a packet!
- But... buffers could be large, but not endless.
- Good for absorbing bursts, but don't help if long-term incoming rate > outgoing rate.
- Actually make things worse (high latency, "bufferbloat") so we don't want to have even to have endless buffers if we could.

### **TCP Self-clocking**





Equilibrium state is good, but... if you are the only one sender, you're already in it and there are no other variables.

Looks unrealistic.

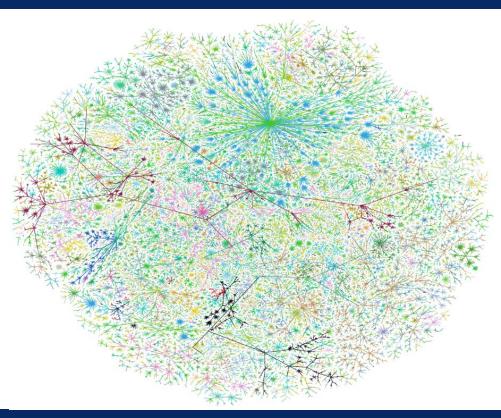
## But in real world...



What about this topology?

- Random data transfers
- Random link parameters
- Unknown path

TCP has to do it's job in this environment.





## How to handle it?



Who must be responsible for handling?

Main decision made in [J88]:

### "Smart endpoint, Dumb internet"

A sender (endpoint) has to slow down its transmission speed for some time giving up self-interest for the interest of the whole system.

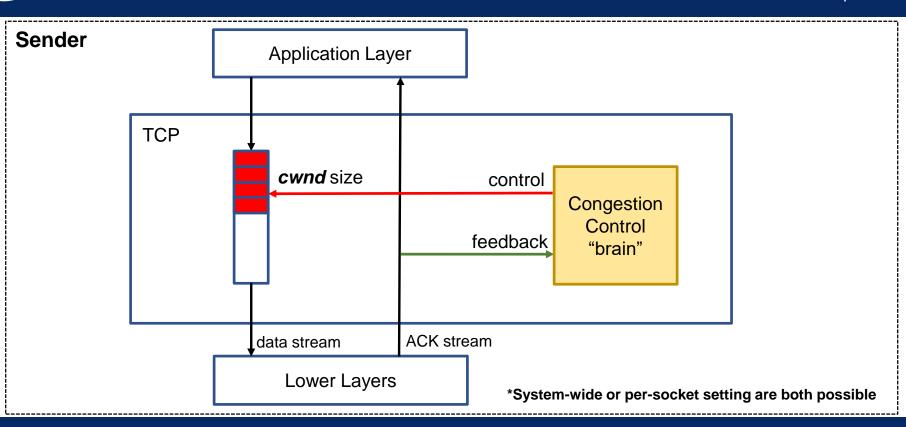
Modified sender should be capable to handle congestion without any assistance from network nodes (though sometimes we'd like to have it... see later).



### Focus on sender



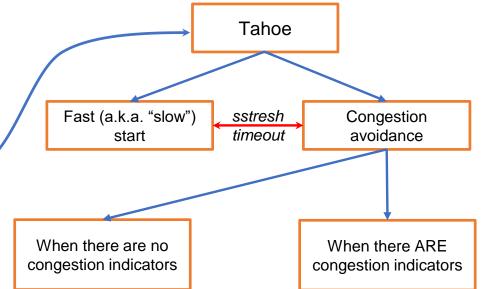
## Design by [J88]



# First solution by [J88]



- Window-based control hello, cwnd! W=min(cwnd, awnd), \* where W – number of unacknowledged packets; we also assume there are no constraints in awnd in this session.
- 2. Feedback: packet loss as network congestion indicator
- Action profile: several stages for different purpose each
- 4. RTO estimation enhancement
- 5. Fast retransmit mechanism
- 6. Focus on <u>protection from collapse</u>, not efficiency etc.



#### Two tasks: 15000000 Establishing ACK clocking circuit (main one!)

- "Fast and dirty" probe for bandwidth.
- Determining initial **sstresh** value for further use. 3.

#### Operation:

1.

- Start from initial window IW.
- For every ACKed SMSS increase *cwnd* by one SMSS.

\*Refer to Christian's session for details



Initial window size nowadays usually equals 10 packets.

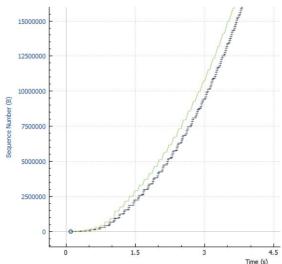
Refer to this link: https://iw.netray.io/stats.html You can change it in Linux OS: #ip route change default via ip.address dev eth0 initcwnd 15 And in Windows OS: https://andydavies.me/blog/2011/11/21/increasing-the-tcp-initial-congestion-window-onwindows-2008-server-r2/

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# Tahoe – "slowfast kickstart"



Client.pcapn



### Fun fact



As *cwnd* increases/decreases at least by SMSS value, its real graph never contains Fun fact inclined line segments, but only horizontal or vertical segments! So: Additive Increase Multiplicative Decrease algorithm Congestion Packet Loss Window size Slow Start Congestion Avoidance 15 1.8 15 Time Time This is technically inaccurate! But totally OK to see In reality it is like that the whole picture

# Tahoe – Congestion avoidance



#### Core ideas:

- 1. Uses packet loss as a sign of congestion (<u>feedback</u> <u>type/input</u>).
- 2. Uses AIMD approach as action profile (control/output).

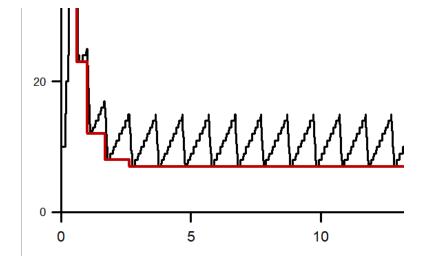
#### Has two modes (as any other algorithm):

- 1. With no observed signs of congestion.
- 2. With signs of congestion detected.

#### cwnd control rules:

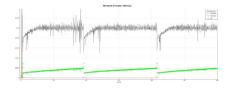
$$cwnd = \begin{cases} cwnd + a & if congestion is not detected \\ cwnd * b & if congestion is detected \end{cases}$$

For Tahoe, Reno 
$$a = \frac{1}{cwnd}$$
;  $b = 0.5$ 



\*Refer to Christian's session for more details

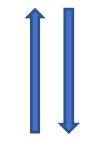




Tahoe was created using "bottom-up" approach: packetlevel rules first, macroscopic view (flow-level) second.

All subsequent CA algorithms (almost) were developed using the opposite "top-down" approach: flow-level first (this is what I want to achieve / address), packet-level rules second (this is how I achieve that).





Packet level

cwnd = {

cwnd + a if congestion is not detected cwnd \* b if congestion is detected



Have you ever though about: why AIMD? Not MIMD, AIAD, MIAD?

The answer is simple – its behavior is the best among others.

- MIAD  $\rightarrow$  not stable, tends to overload a network.
- MIMD  $\rightarrow$  less fairness
- AIAD  $\rightarrow$  less fairness
- AIMD → tends to achieve efficiency + fairness. "React quickly to bad news, react slowly to good news".



#### True or False?

• AIMD is an obsolete congestion control algorithm, nowadays we have better ones.

#### True or False?

• All congestion control algorithms since Tahoe react to packet loss.

#### True or False?

 cwnd in Reno in Congestion Avoidance phase grows as straight line until packet loss is detected.



#### True or False?

- AIMD is an obsolete congestion control algorithm, nowadays we have better ones Partially true!
- True: AIMD itself is not a congestion control algorithm, this is just an approach, pattern to behave while in congestion control stage. Many modern algorithms also use AIMD approach, but it's being eventually switched from. Remember also: <u>AIMD ≠ Reno</u>

#### True or False?

- All congestion control algorithms react to packet loss FALSE!
- True: There many kinds of congestion control algorithms. Many of them indeed react to packet loss, but many others use different feedback type delay. So, transition to congestion avoidance state could be done with no observed packet loss at all!

#### True or False?

- *cwnd* in Reno (CA stage) grows as straight line until packet loss is detected FALSE!
- True: In addition to "staircase-shape" although this line looks straight, it is not! The more *cwnd* size is, the less slope of this line is (refer to "Convergence" slide to see it!). Chances are we'll reach packet loss too early to spot this.



## Let's rate it!

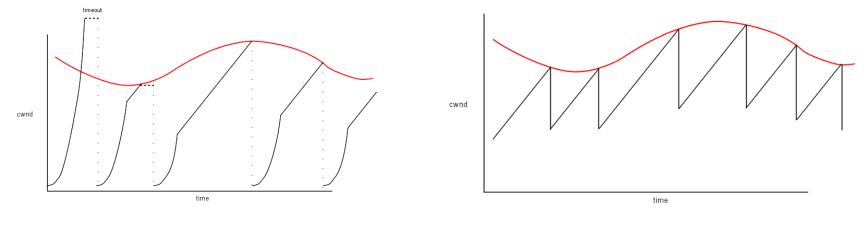


Well, how to decide which algorithm is better?

- 1. Efficiency (how full and steady is bottleneck utilization?)
- 2. Fairness (how we share bottleneck capacity?)
- 3. Convergence capability (how fast we approach equilibrium state? How much we oscillate later?)
- 4. "Collateral damage" (buffer overflow event rate, selfinflicted latency)

### Efficiency





Tahoe: bad

Reno: better, but not ideal

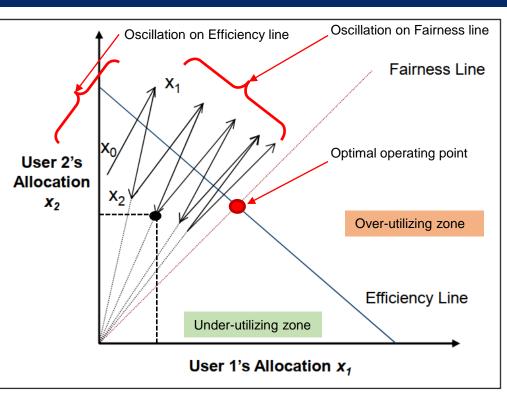




Introducing: Phase graph

Shows efficiency, fairness and convergence.

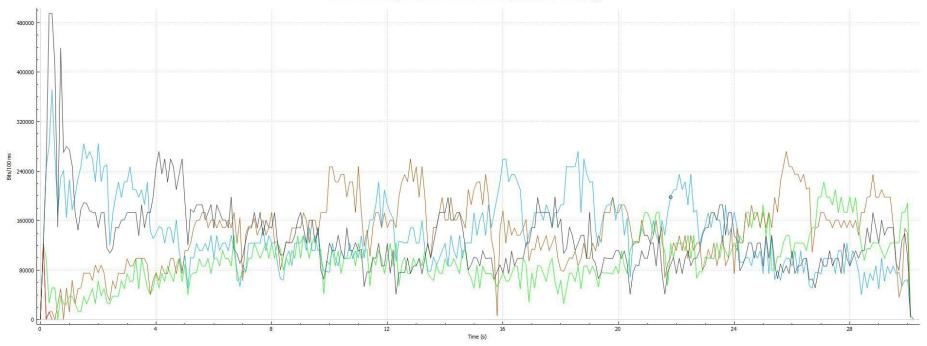
Here: an example for two senders.



# Fairness (5 streams Reno)



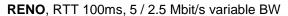
Wireshark IO Graphs: Realtek PCIe GBE Family Controller: eth0 (tcp)

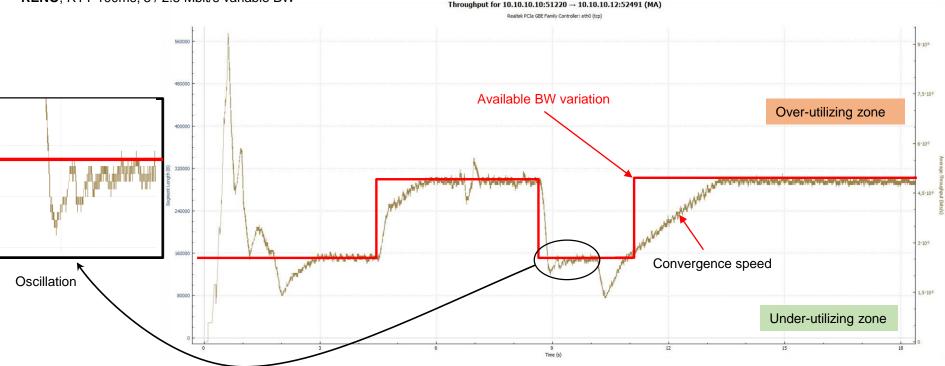


But what about non-TCP protocols? See later..

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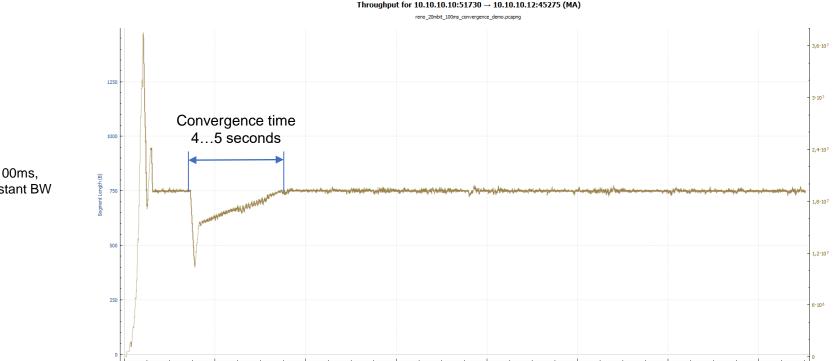
## Convergence (1 stream)





# Convergence (1 stream)





16

Time (s)

20

24

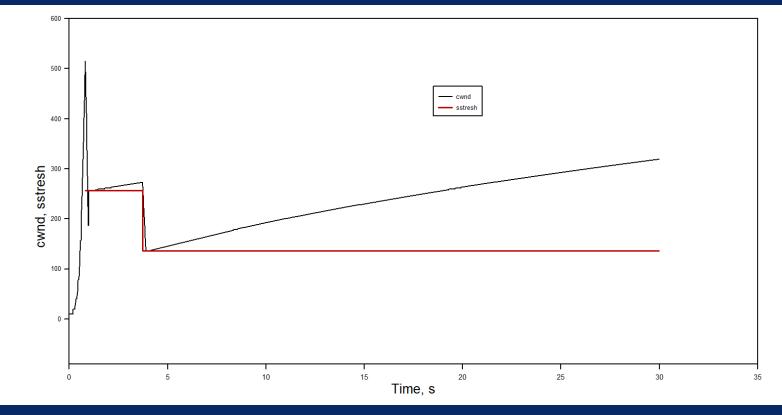
28

**RENO**, RTT 100ms, 20 Mbit/s constant BW

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**RENO**, RTT 100ms, 20 Mbit/s constant BW

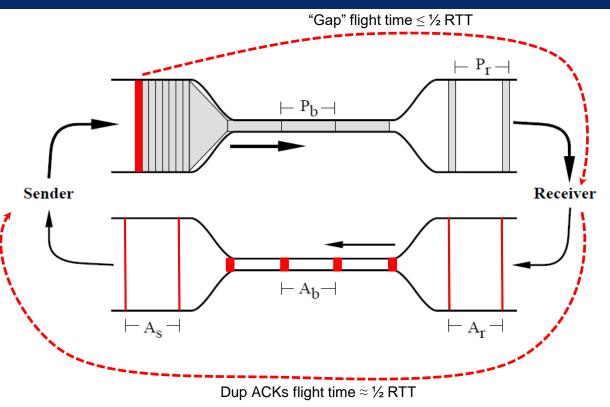
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## Complex challenges - 1



#### "Late news!"

- The sender will know about "data leaving network rate" not instantly, but only after ½ RTT.
- With packet drop at the beginning of a path it's getting worse.
- All this time the sender was sending more and more packets! Probably already starting to slide down the cliff.
- It is getting worse when RTT increases.







#### Non-TCP-compatible flows, unresponsive flows ("fairness" and "TCP friendliness").

- ✓ Non-TCP-compatible is a flow which reacts to congestion indicators <u>differently</u>, not like TCP.
- ✓ Unresponsive is a flow which does not react to congestion indicators <u>at all</u>.

"Fairness"	"TCP friendliness"
This is how TCP flows with the same CA	This is how non-TCP flows or TCP flows with
algorithm share bottleneck BW with each other.	different CA algorithms share bottleneck
A part of it is "RTT fairness".	bandwidth.

#### 2 possible solutions of this problem:

- ✓ TCP friendly rate control [RFC5348] concept intentional rate limiting. \* a part of many modern CA algorithms.
- ✓ Call for help ("network assisted congestion control").



A REAL

**Core idea**: create an equation for T (sending rate, packets/RTT) with argument *p* (packet loss coefficient).

T=f(p)

For standard TCP (Reno) the equation is:

$$T = \frac{1.2}{\sqrt{p}}$$

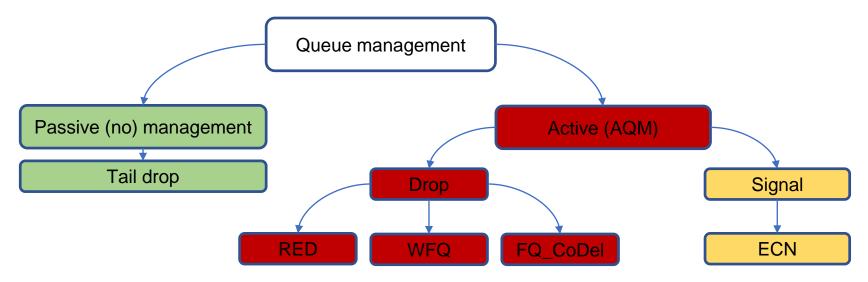
- ✓ Comparing actual T to "Reno –T" we can analyze *relative fairness* i.e. how aggressive protocol is vs. standard TCP.
- ✓ Equations might be much more complex and take into account RTT, packet size.

## Call for help!



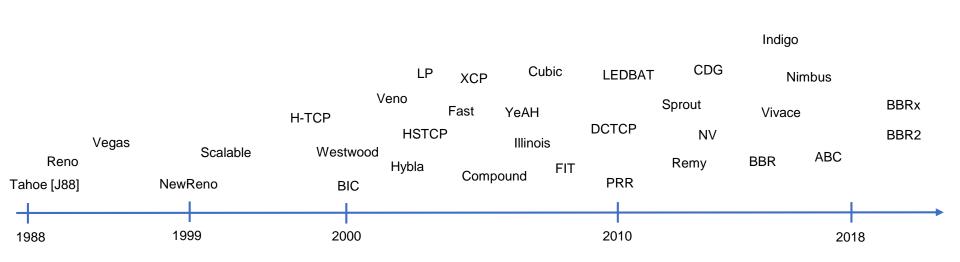
Sometimes this isn't enough so to **ask network for help** is a good idea!

- ✓ Routers know their own state (buffer load, link speed).
- ✓ Router can separate different kinds of flows.



### Timeline











Core idea: Tahoe + "Fast Recovery".

#### What do we address: non-optimal behavior during loss recovery.

#### **Operation:**

- Send Fast retransmission and then:
- Set *sstresh* to *cwnd*/2, set *cwnd* to *sstresh*+3.
- Increase *cwnd* on 1 SMSS for every received next Dup ACK ("inflate phase").
- Decrease *cwnd* to *sstresh* after receiving higher ACK ("deflate phase").

Reason: we treat Dup ACKs stream as **good** sign (because packets somewhere are leaving our network!) But we are stuck with "unacknowledged" window edge because of packet loss and can't use capacity becoming available. So let's manipulate **cwnd** temporarily for this period and bring things back when it ends.



This is Reno + improved packet loss handling (only for multiple segments loss).

#### What do we address: loss burst.

#### Reason:

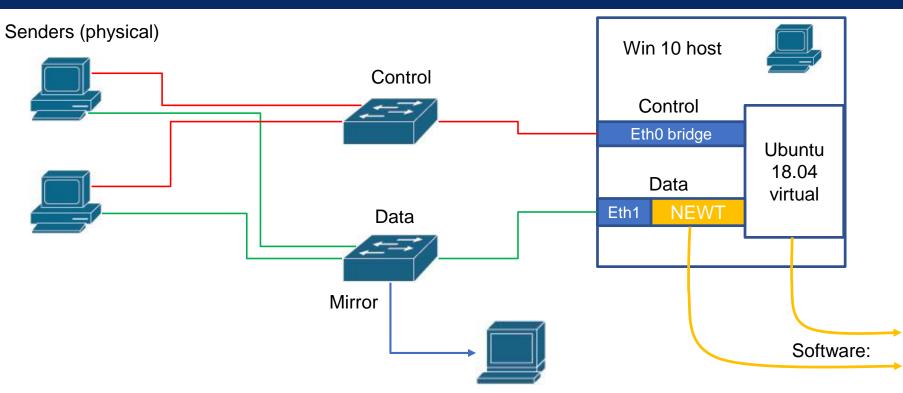
If multiple segments were lost, this can mess up our "inflate-deflate" strategy. We'll deflate *cwnd* even if we receive *partial ACK* (higher than the one in Dup ACK stream, but lower than packet we sent last before loss). Therefore we'll deflate *cwnd* too early!

#### Solution:

- Remember highest SEQ at the moment of packet loss detection ("Recovery point").
- Do NOT deflate *cwnd* unless we receive an ACK for Recovery Point.

### Test system





### Software 1 - NEWT



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	Remote IP	FFFF	:	FFFF	:	FFFF	:	FFFF	:	FFFF	:	FFFF	:	FFFF	:	FFFF
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https://blog.mrpol.nl/2010/01/14/network-emulator-toolkit/

## Software 2 - flowgrind



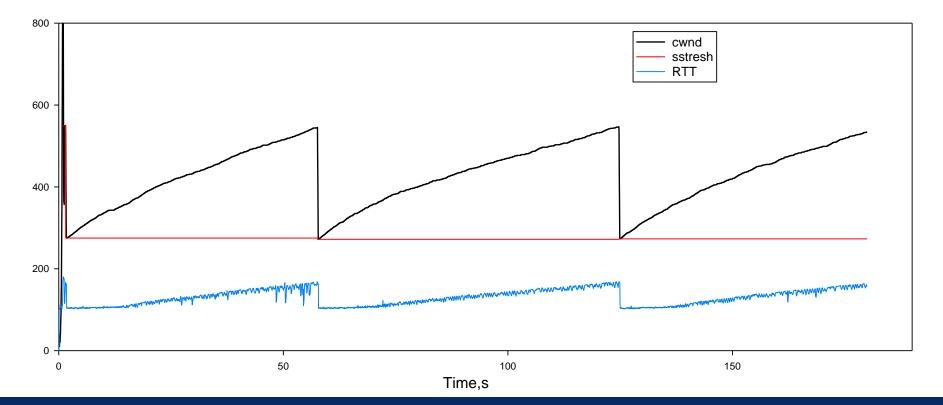
$\checkmark$	Allows separation between control and data
	traffic.

- Large number of monitored values (including current *cwnd* and *sstresh* size, yeah!)
- ✓ Various traffic generation patterns.
- ✓ Individual TCP flow parameters setting.
- An ability to start flow from any PC running flowgrind daemon.
- Possibility to redirect output table to text file for parsing.
- Sensitive to incorrect arguments (often gets stuck and reboot is needed).
- Problems with NAT'ed endpoints.
- No Windows version = no Compound TCP.

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http://manpages.ubuntu.com/manpages/bionic/man1/flowgrind.1.html





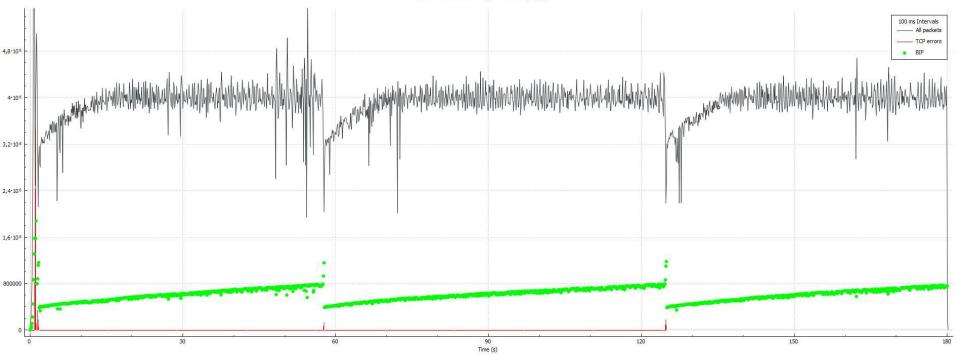
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### NewReno



Wireshark IO Graphs: eth0 (tcp)

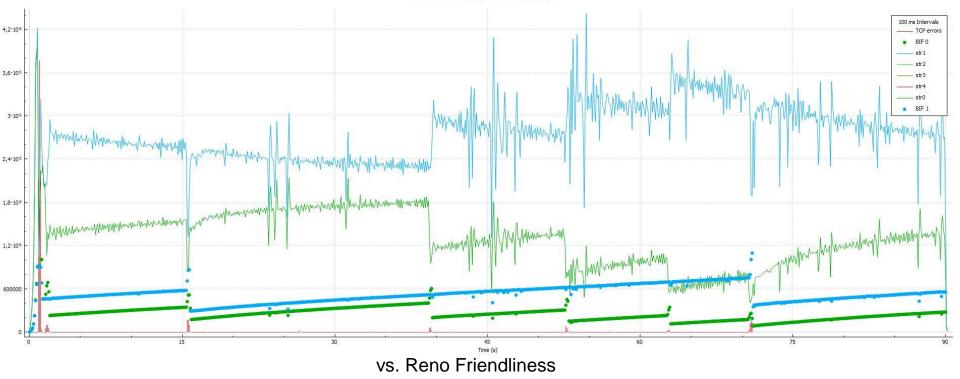


Collateral damage: Almost 3 Buffer overflows / 797k Total Packets







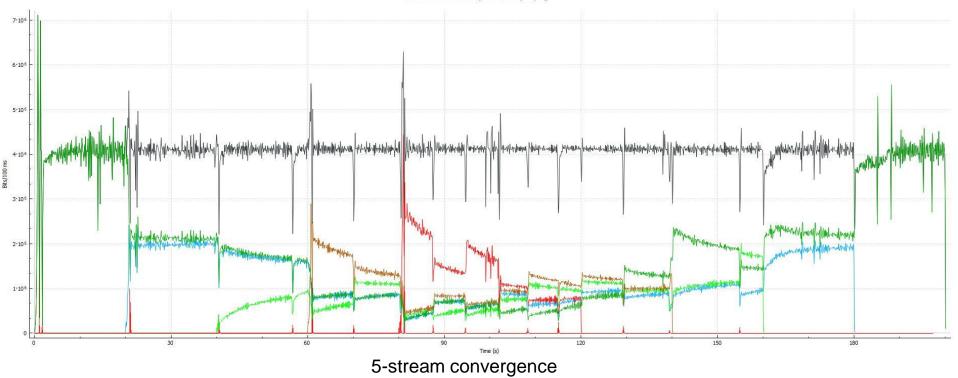








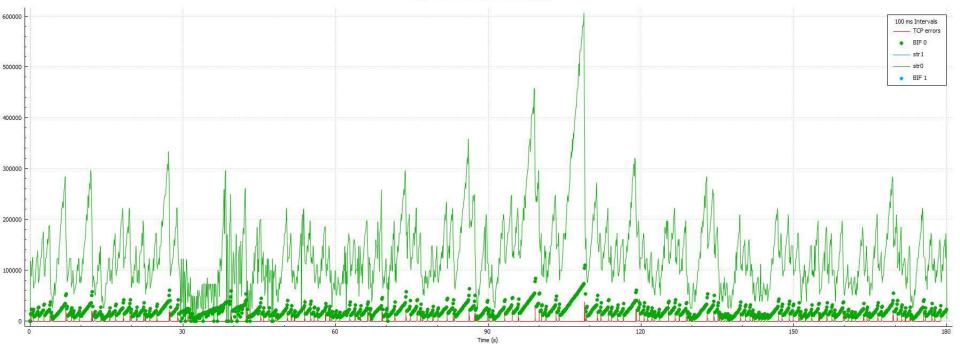
Wireshark IO Graphs: reno.pcapng











1% loss link behavior

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### Further progress



#### Several problems were observed with Reno:

- NewReno was doing its job fine those days, but later with the raise of LFN and wireless it became clear that...
- It can't work efficiently on high-BDP links (because *cwnd* fixed additive increase algorithm is too slow and ½ *cwnd* drop is too much). To utilize fully 1Gbps link with 100ms RTT it needs packet loss rate of 2x10<sup>-8</sup> or less. With 1% loss in this link it can't go faster than 3Mbps. After packet loss event it needs 4000 RTT cycles to recover.
- × It treats <u>any</u> packet loss as congestion indicator (not good for wireless networks).
- × Often visits "cliff" area (this is common among all loss-based algorithms).
- Has 1-Bit congestion indicator = inevitable high oscillation level (this is common among all loss-based algorithms).

### Further progress



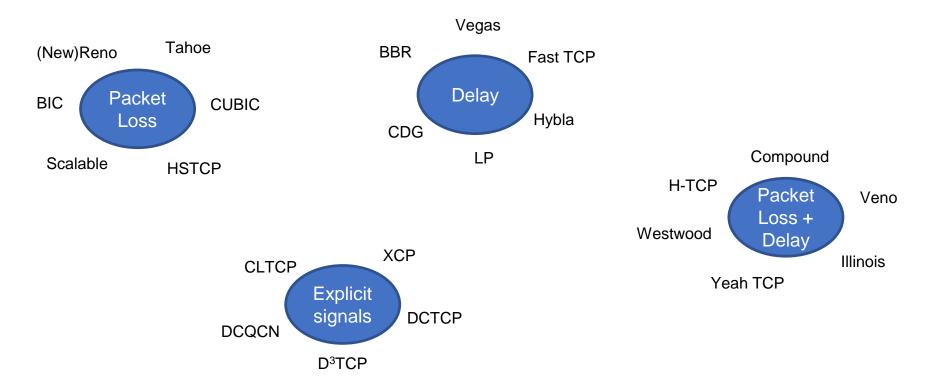
How to make CC algorithm perform better? What to play with? Remember feedback type and control? Let's play with them!

#### Feedback type:

- Packet loss
- Delay
- Both of them
- ACKs inter-arrival timing
- Explicit signals (ECN)

### CA – feedback types





#### We can play with *a* factor Not constant a, but a=f(something)cwnd + a if congestion is not detected cwnd \* b if congestion is detected Same with b.

CA – control (action) tweaking

What about control?

cwnd = {

**Step 1.** Playing with AIMD factors.

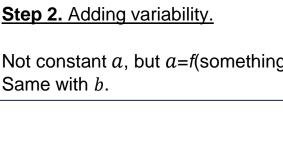
**Bandwidth** b а Time

Therefore changing angle and "drop height".

We can play with b factor

**Step 3.** Shifting from AIMD to entirely different model. (The most recent approach).







# Scalable TCP – first "high BDP" try

#### Core ideas:

"Psycho"

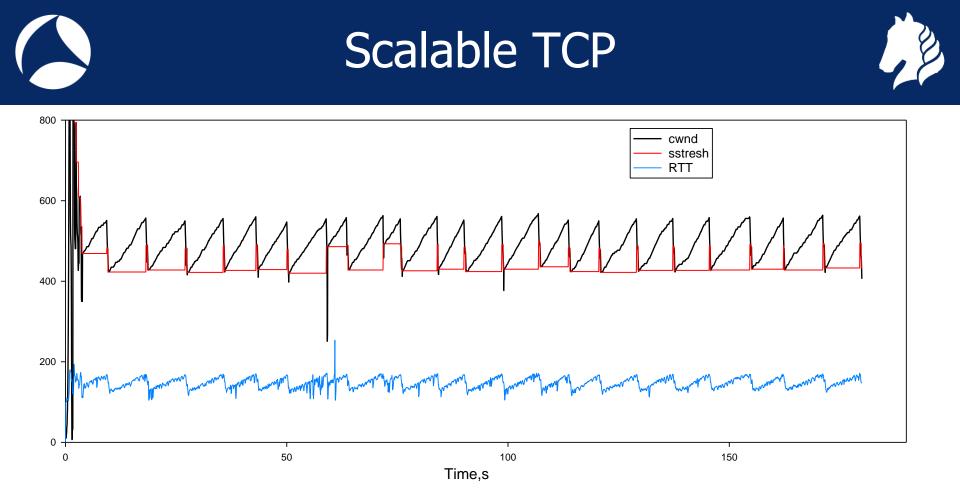
#### <u>Source</u>

- 1. Aimed to deal with high BDP (first and simplest attempt to do it).
- 2. Uses packet loss as feedback (loss-based).
- 3. Uses MIMD approach as action profile (!).

#### cwnd control rules:

 $cwnd = \begin{cases} cwnd + 0.01 * cwnd & if congestion is not detected \\ cwnd * 0,875 & if congestion is detected \end{cases}$ 

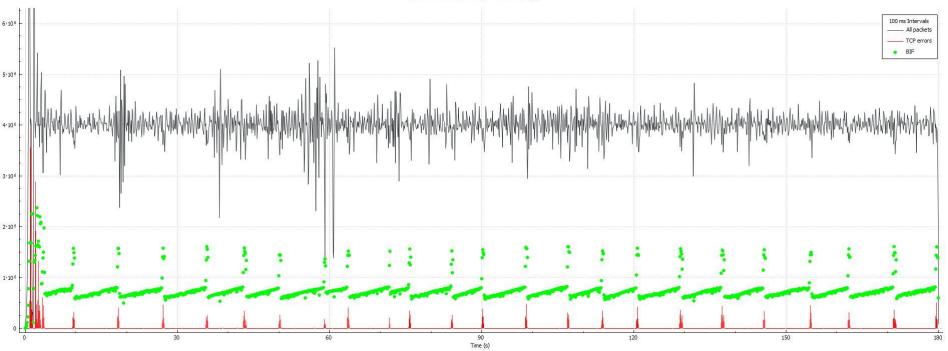
- ✓ Much more efficient than Reno in high BDP networks.
- ✓ Recovery time after packet loss (200ms RTT, 10Gbps link) 2,7 sec.
- × RTT fairness, TCP friendliness terrible. Kills Reno easily.



### Scalable TCP



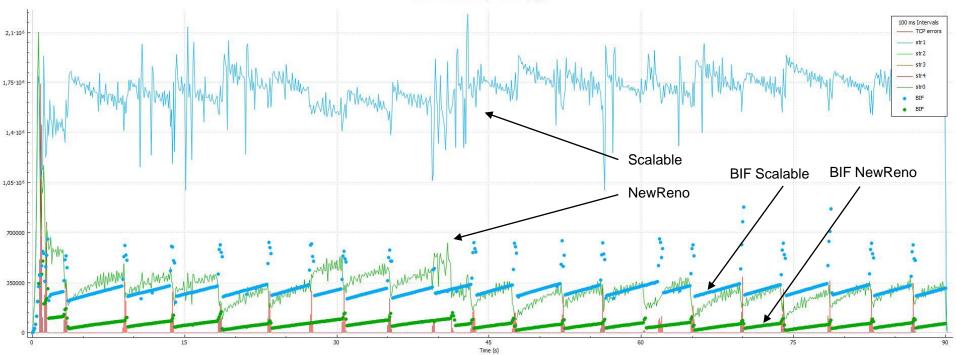




Collateral damage: 23 Buffer overflows / 812k Total Packets

### Scalable vs NewReno

Wireshark IO Graphs: eth0 (tcp)



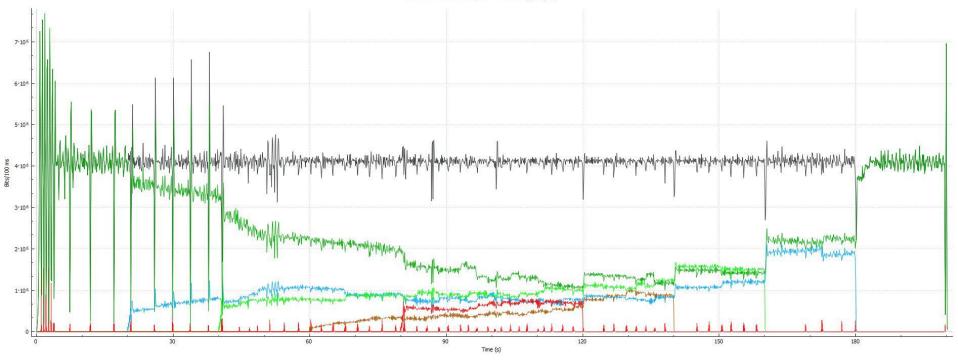
It's unfair to say the least. 20Mbps, 100ms link.







Wireshark IO Graphs: scalable.pcapng



5-stream convergence

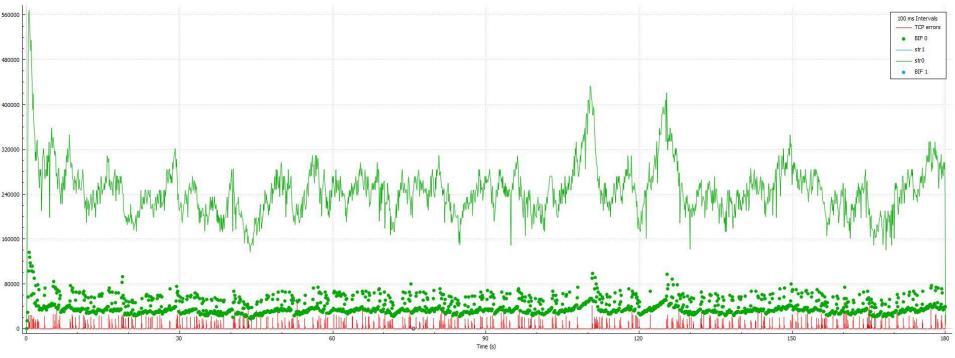
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Wireshark IO Graphs: eth0 (tcp)



1% loss link behavior

### Highspeed TCP [RFC 3649]

Source



#### Core ideas:

#### "Medicated psycho"

- 1. Aimed to deal with high BDP.
- 2. Uses packet loss as feedback (loss-based).
- 3. Uses AIMD approach as action profile.
- 4. "Let's live with Reno on low-BDP, but take what it can't take on high-BDP"

#### cwnd control rules:

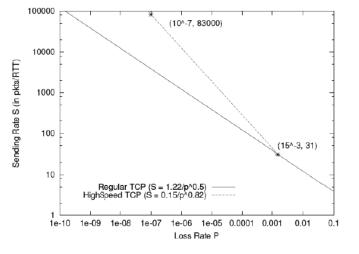
$$cwnd = \begin{cases} cwnd + a(cwnd)/cwnd & if congestion is not detected \\ cwnd - b(cwnd) * cwnd & if congestion is detected \end{cases}$$

#### **Formula:** $a(w) = 2P_0 W_0^2 b(w)/(2 - b(w))$

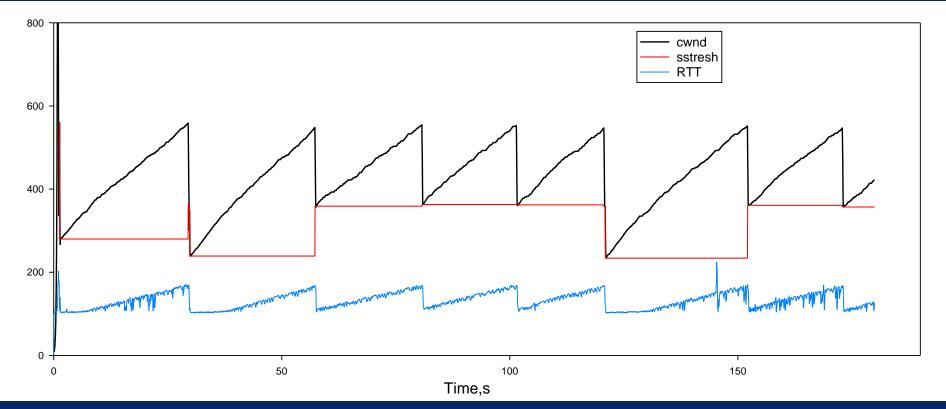
<u>Main point is</u>: *a*, *b* values depend on current *cwnd* size. If *cwnd* is less than 38\*SMSS -> act as Reno (more bits in input!)

• Behaves less aggressive if a path is not LFN (for TCP friendliness).

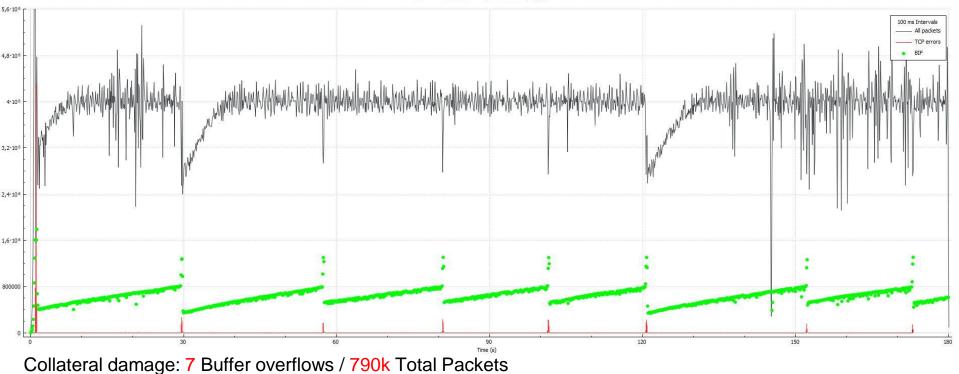
× RTT fairness - still bad.





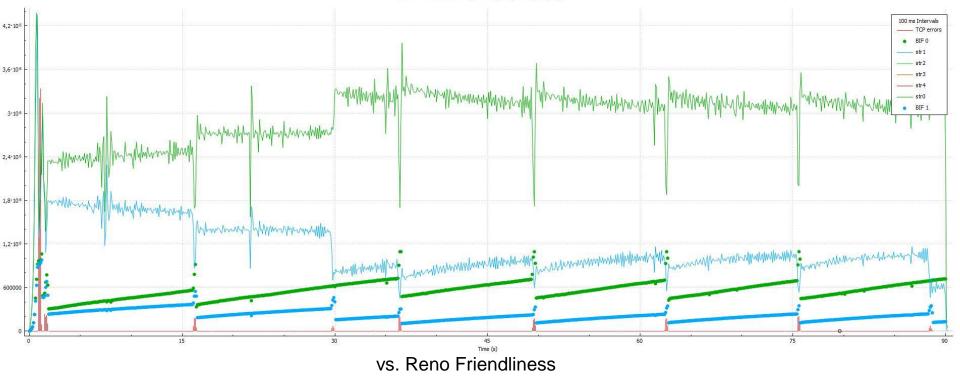


Wireshark IO Graphs: eth0 (tcp)



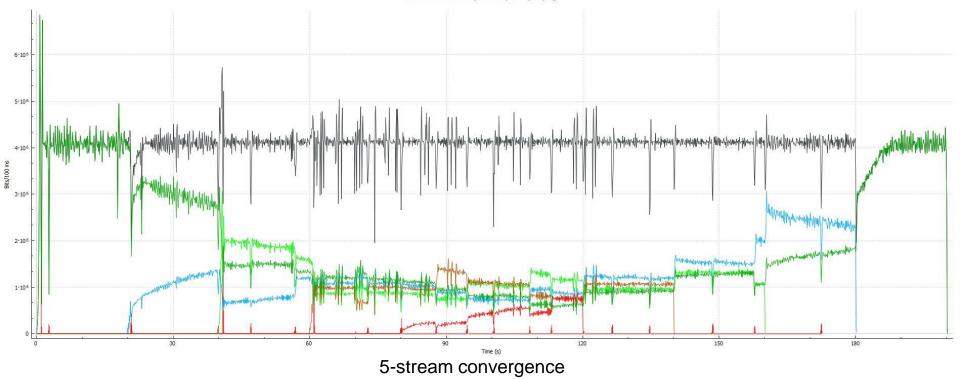






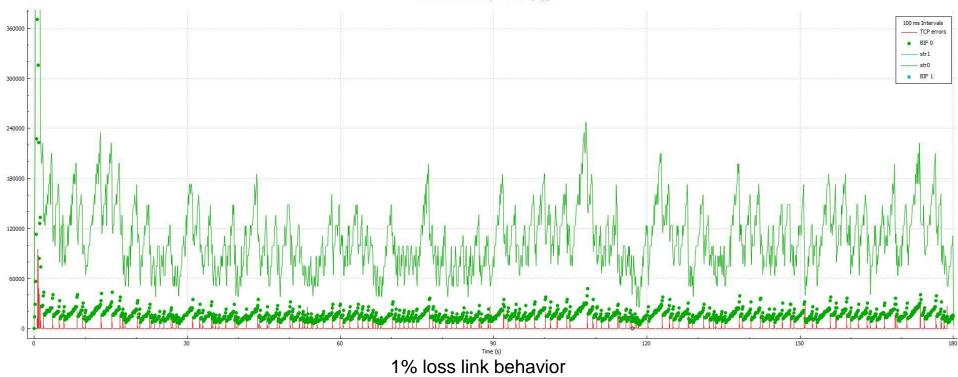


Wireshark IO Graphs: hispeed.pcapng





Wireshark IO Graphs: eth0 (tcp)



Source





#### "Ready-Steady-Go!"

- 1. Aimed to deal with high BDP.
- 2. Uses packet loss as feedback.
- 3. Uses cubic function as action profile (concave/convex parts).
- 4. Default for all Linux kernels > 2.6.18, implemented in Windows since Win10.

#### cwnd control rules:

In case of packet loss:

- Set W<sub>max</sub> to *cwnd*;
- 2. Set *cwnd*, *sstresh* to  $(1 \beta)^*$ *cwnd* where default  $\beta = 0.8$
- 3. Grow *cwnd* using cubic function:

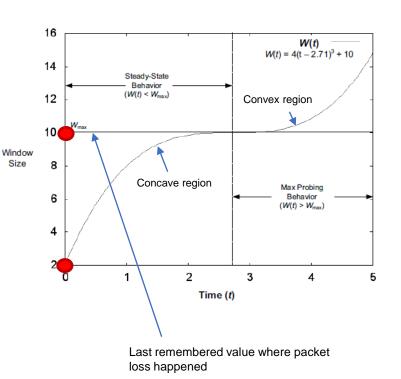
W(t) = C(t - K)<sup>3</sup> + W<sub>max</sub> where: 
$$K = \sqrt[3]{\frac{\beta W_{max}}{C}}$$

<u>**Main point</u>**: approach last packet loss point slowly and carefully, but <u>if</u> there is no more packet loss here – begin ramp up to use possibly freed up resources.</u>

<u>Additional techniques used</u>: TCP friendly region, Fast convergence, Hybrid slow start.

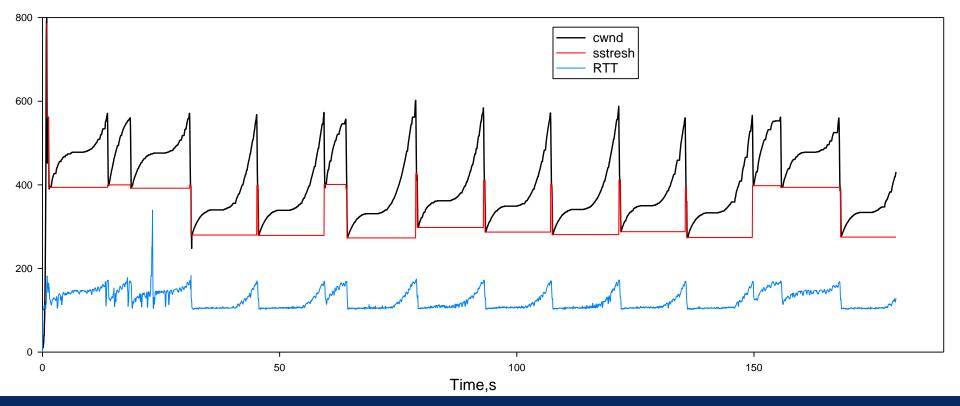
✓ Coexistence with Reno on non-LFN links – moderate

✓ RTT fairness - good





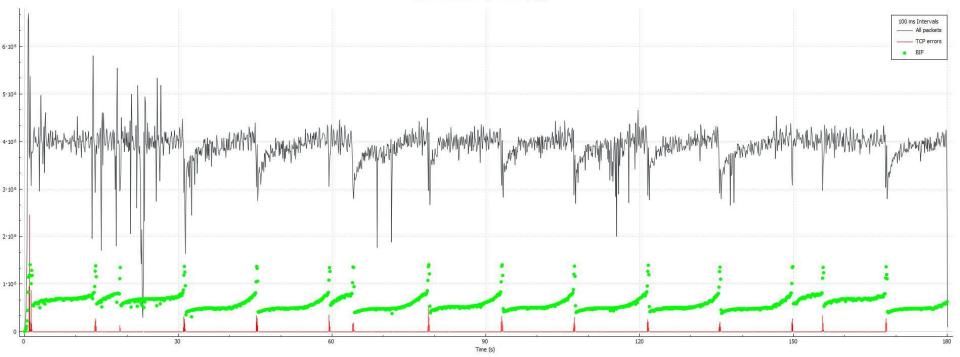




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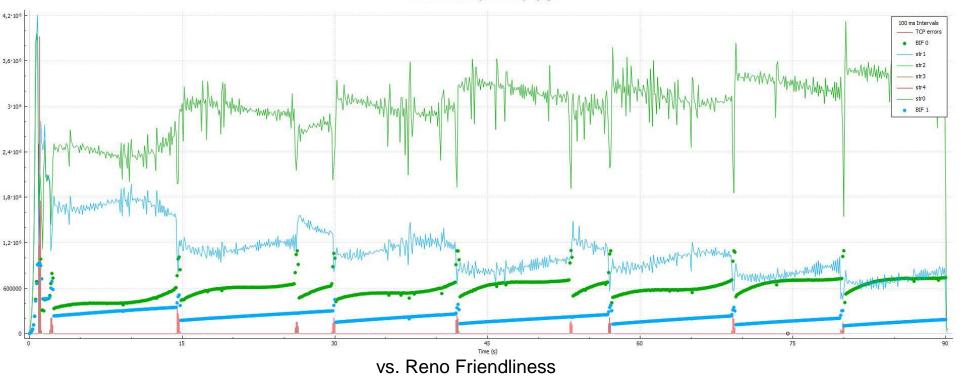


Collateral damage: 14 Buffer overflows / 790k Total Packets



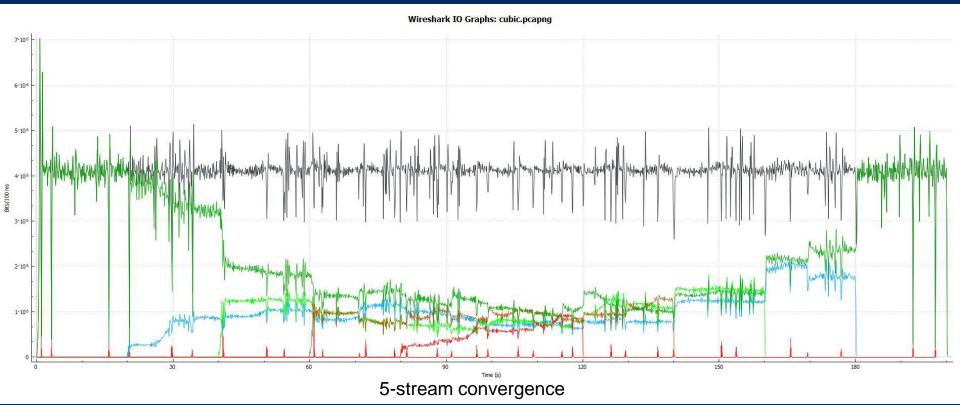


Wireshark IO Graphs: cubic.pcapng





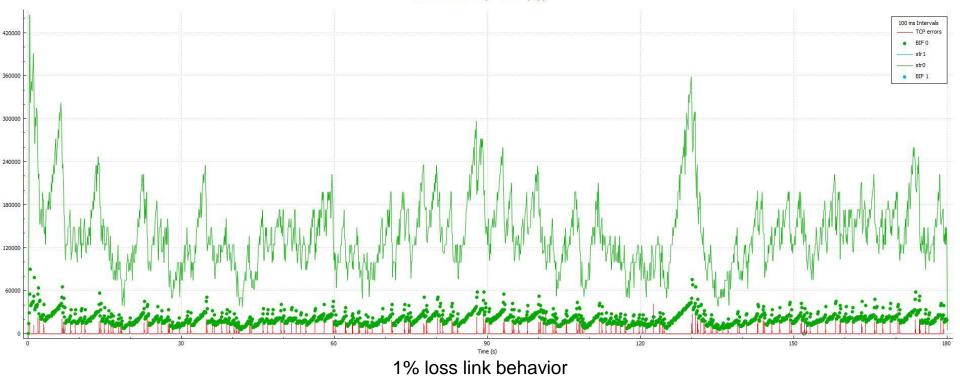








Wireshark IO Graphs: eth0 (tcp)

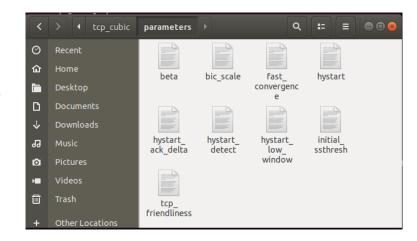


### **CUBIC Fun Fact**



If you look at CUBIC source code you'll spot some parameters can be tweaked!

/\* Note parameters that are used for precomputing scale factors are read-only \*/ 61 62 module\_param(fast\_convergence, int, 0644); MODULE\_PARM\_DESC(fast\_convergence, "turn on/off fast convergence"); 63 64 module\_param(beta, int, 0644); 65 MODULE\_PARM\_DESC(beta, "beta for multiplicative increase"); 66 module\_param(initial\_ssthresh, int, 0644); MODULE\_PARM\_DESC(initial\_ssthresh, "initial value of slow start threshold"); 67 68 module\_param(bic\_scale, int, 0444); 69 MODULE\_PARM\_DESC(bic\_scale, "scale (scaled by 1024) value for bic function (bic\_scale/1024)" 70 module\_param(tcp\_friendliness, int, 0644); MODULE\_PARM\_DESC(tcp\_friendliness, "turn on/off tcp friendliness"); 71 72 module\_param(hystart, int, 0644); 73 MODULE\_PARM\_DESC(hystart, "turn on/off hybrid slow start algorithm"); 74 module\_param(hystart detect, int, 0644); 75 MODULE\_PARM\_DESC(hystart\_detect, "hybrid slow start detection mechanisms" 76 " 1: packet-train 2: delay 3: both packet-train and delay"); 77 module\_param(hystart low window, int, 0644); 78 MODULE\_PARM\_DESC(hystart\_low\_window, "lower bound cwnd for hybrid slow start"); 79 module\_param(hystart\_ack\_delta, int, 0644); 80 MODULE\_PARM\_DESC(hystart\_ack\_delta, "spacing between ack's indicating train (msecs)"); **Q1** 



These knobs can be found (for Ubuntu) at /sys/module/tcp\_cubic/parameters

### Hybrid slow start



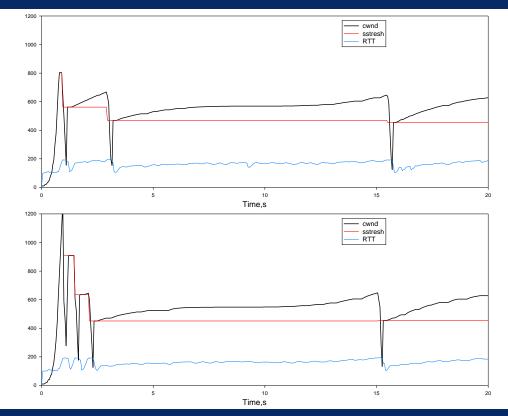
**Problem:** high aggressiveness during final slow start phase.

**Solution:** estimate a point where to exit Slow Start mode.

#### Methods:

- ACK train length measuring method.
- Inter-frame delay method.

Built-in in CUBIC algorithm.





### VEGAS TCP

Source



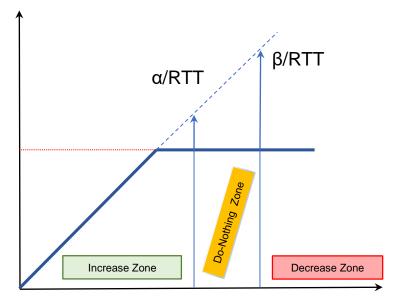
#### Core ideas:

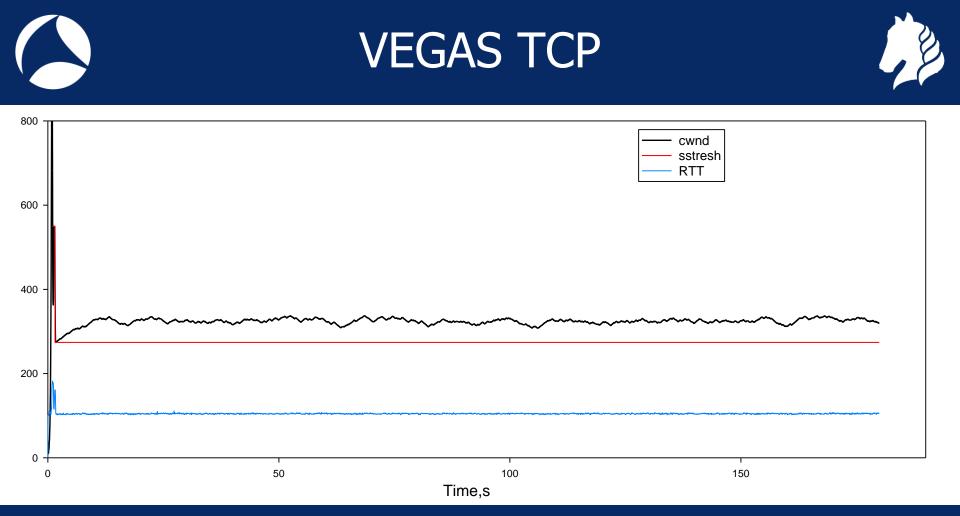
"Pacifist"

- 1. First try to build delay-based algorithm (1994).
- 2. Uses delay as feedback (purely delay-based).
- 3. Uses AIAD as action profile.

#### cwnd control rules:

- 1. Measure and constantly update min RTT ("BaseRTT")
- 2. For every RTT compare Expected Throughput (*cwnd* / BaseRTT) with Actual Throughput (*cwnd* / RTT)
- 3. Compute difference = (Expected Actual)/BaseRTT
- 4. Look where in range it lies and act accordingly (1 per RTT *cwnd* update frequency).
- 5. Switch to Reno if there are not enough RTT samples.
- ✓ Very smooth
- ✓ Doesn't act on Cliff zone
- ✓ Induces small buffer load, keeps RTT small
- × Gets beaten by **any** loss-based algorithm
- Doesn't like small buffers
- × Doesn't like small RTTs





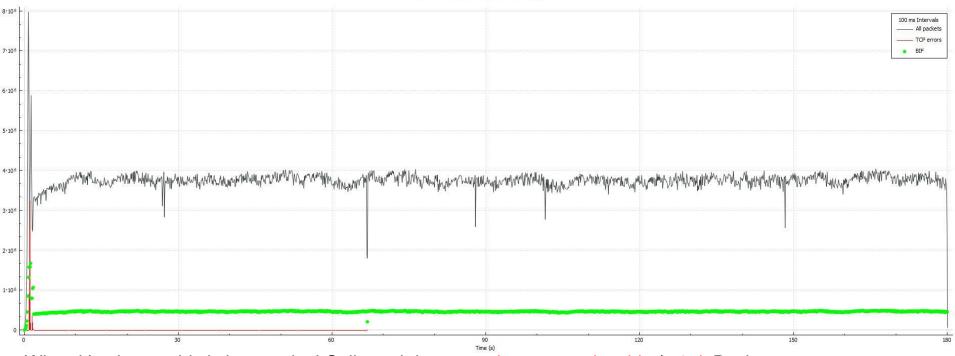
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### VEGAS TCP



Wireshark IO Graphs: eth0 (tcp)



When it's alone – this is impressive! Collateral damage: almost unnoticeable / 767k Packets

### NewReno vs. VEGAS TCP

Wireshark IO Graphs: eth0 (tcp)

2,4.106 100 ms Intervals TCP error BIF str1 withinghamment when within strí 2.106 BIF MW 1.6.10 NewReno 1,2.10 **BIF Vegas** 800000 VEGAS **BIF NewReno** 400000 White Manufacture 75

When VEGAS is not alone - this is a shame..

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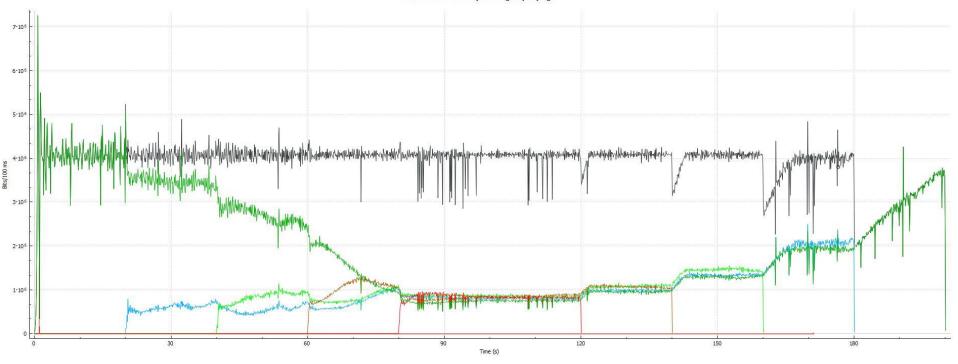
Time (s)



### VEGAS TCP



Wireshark IO Graphs: vegas.pcapng



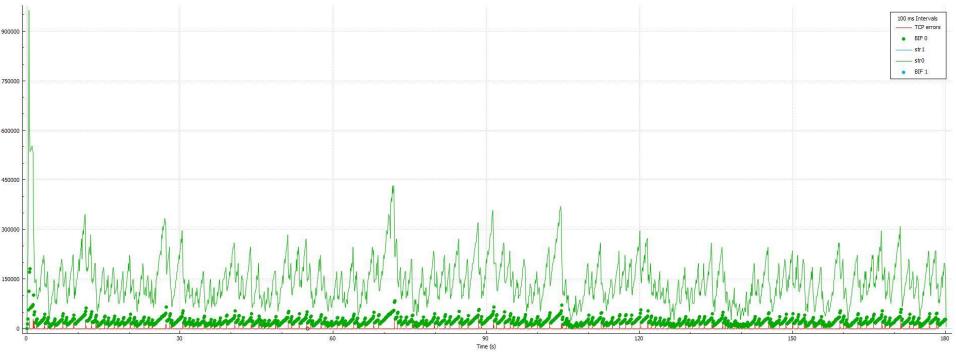
5-stream convergence



### **VEGAS TCP**



Wireshark IO Graphs: eth0 (tcp)



1% loss link behavior

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# ILLINOIS TCP



### Core ideas:

"Careful"

- 1. Uses packet loss and delay as feedback.
- 2. Uses modified AIMD with delay-dependent variables as action profile.

### cwnd control rules:

 $cwnd = \begin{cases} cwnd + \alpha/cwnd & if congestion is not detected \\ (1 - \beta) * cwnd & if congestion is detected \end{cases}$ 

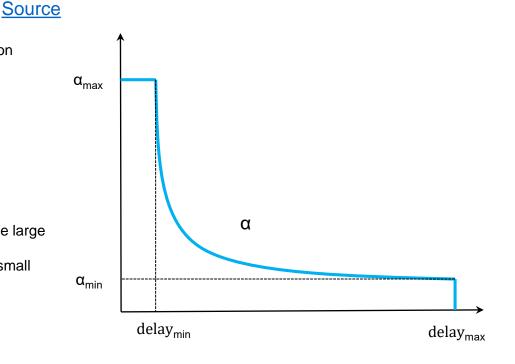
Measure min RTT and max RTT for each ACK. Track them.

### <u>Compute α:</u>

- If average delay is at minimum (we are uncongested), then use large alpha (10.0) to grow *cwnd* faster.
- If average delay is at maximum (getting congested) then use small alpha (0.3)

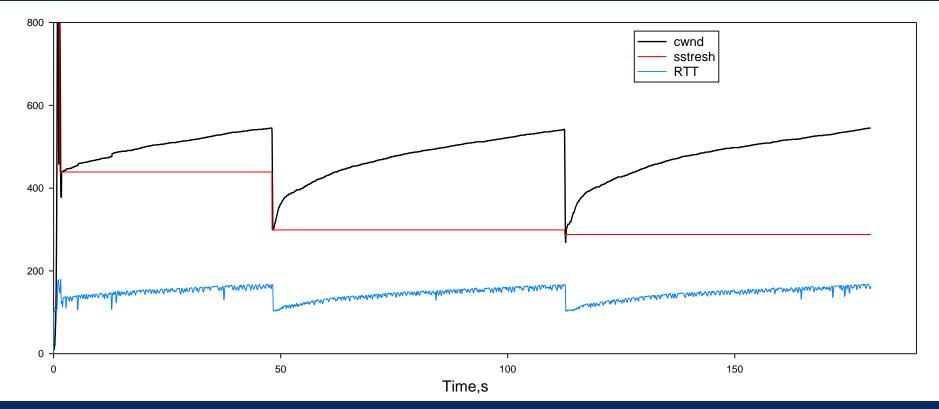
### <u>Compute β:</u>

- If delay is small (10% of max) then  $\beta = 1/8$
- If delay is up to 80% of max then  $\beta = 1/2$
- In between is a linear function



## **ILLINOIS TCP**



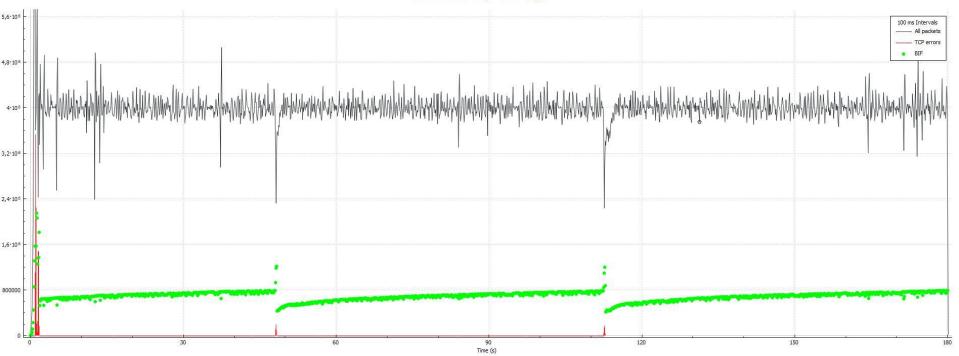


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## ILLINOIS TCP



Wireshark IO Graphs: eth0 (tcp)

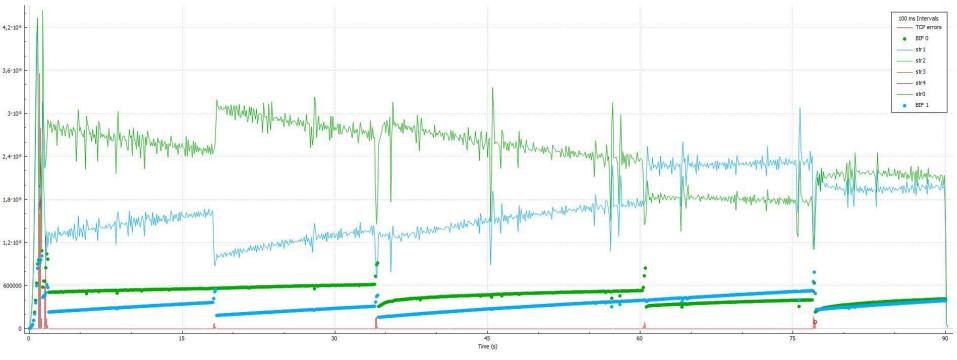


Collateral damage: 2 Buffer overflows / 815k Total Packets

## Illinois TCP







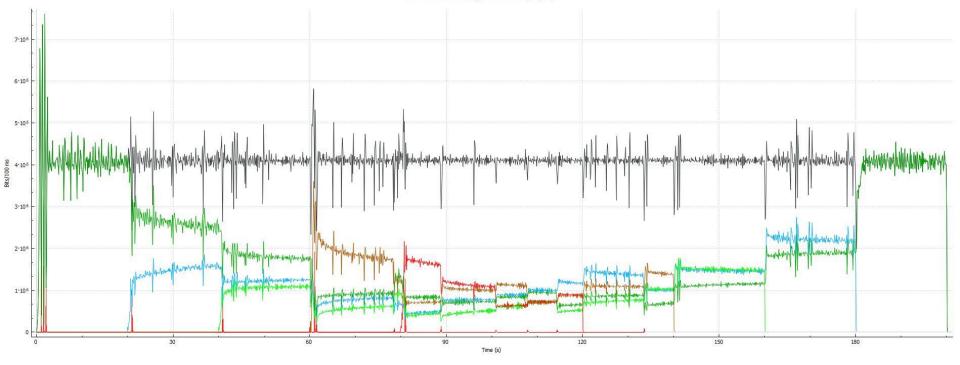
vs. Reno Friendliness



## Illinois TCP





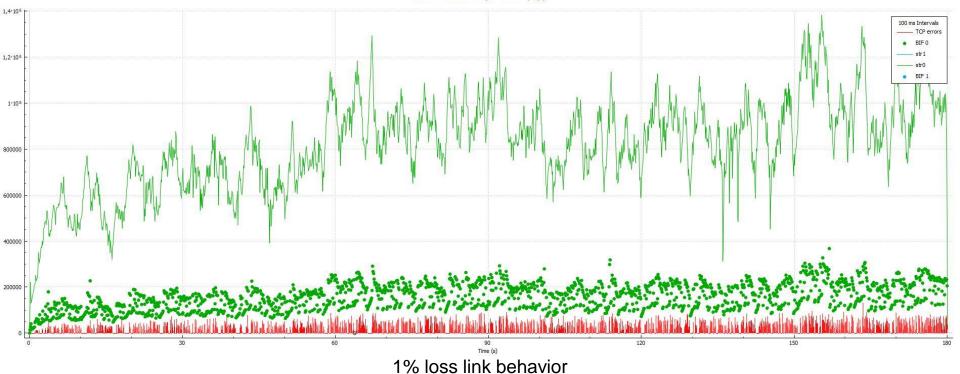


5-stream convergence

## Illinois TCP



Wireshark IO Graphs: eth0 (tcp)



# Compound TCP



### Core ideas:

### "Windows"

- 1. Uses combination of packet loss and delay as feedback.
- 2. Uses AIMD additionally altered by delay window as action profile.
- 3. Only for Windows OS since Vista.

### cwnd control rules:

win = min (cwnd + dwnd, awnd)

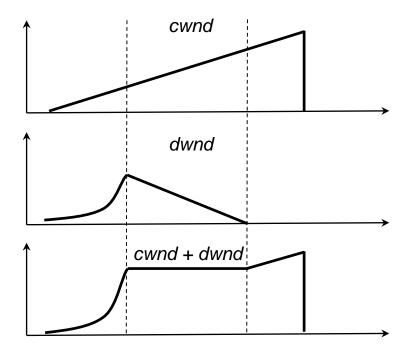
Where: *cwnd* – as in Reno, *dwnd* – as in Vegas.

 $cwnd = \begin{cases} cwnd + 1/(cwnd + dwnd) & if congestion is not detected \\ (1 - \beta) * cwnd & if congestion is detected \end{cases}$ 

Main point: combine fairness of delay-based CA with aggressiveness of loss-based CA.

✓ Coexistence with Reno on non-LFN links – good

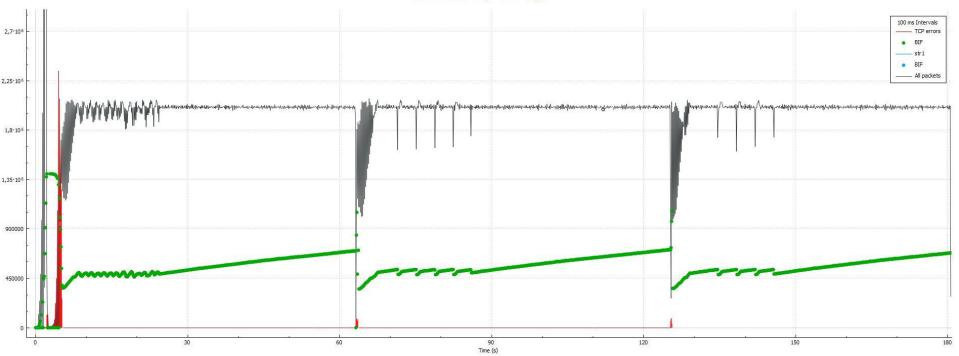
✓ RTT fairness - good



## Compound TCP



Wireshark IO Graphs: eth0 (tcp)



Link: 20mpbs, 200ms RTT. Tested using ntttcp.exe, Win10 – Win10. Sorry, no cwnd graph..





### Core ideas:

"Wireless warrior"

Source

- 1. Main idea: an attempt to distinguish between congestive and non-congestive losses.
- 2. Uses packet loss as feedback.
- 3. Uses modified AIMD as action profile.
- Continuously estimates bandwidth (BWE, from incoming ACKs) and minimal RTT (RTT<sub>noLoad</sub>)

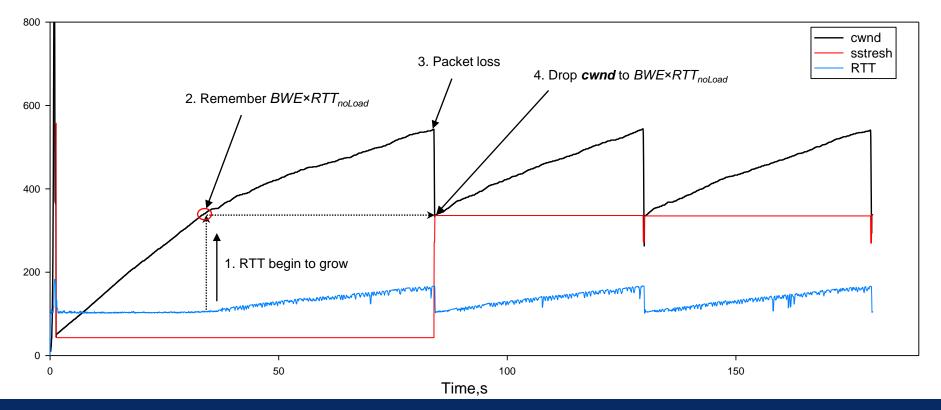
### cwnd control rules:

- Calculates "transit capacity" : BWE×RTT<sub>noLoad</sub> (represents how many packets can be in transit)
- Never drops *cwnd* below estimated transit capacity.

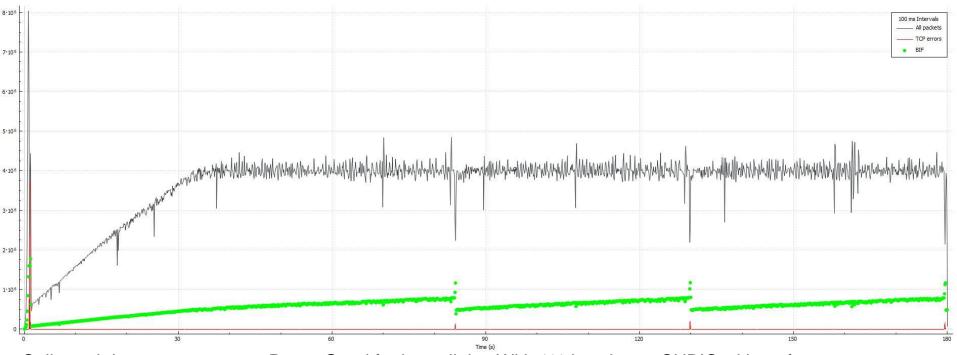
 $cwnd \text{ (on loss)} = \begin{cases} max(cwnd/2, BWE \times RTTnoLoad) \text{ if } cwnd > BWE \times RTTnoLoad \\ no \text{ change, if } cwnd \leq BWE \times RTTnoLoad \end{cases}$ 

• If no loss is observed – acts similarly to Reno.





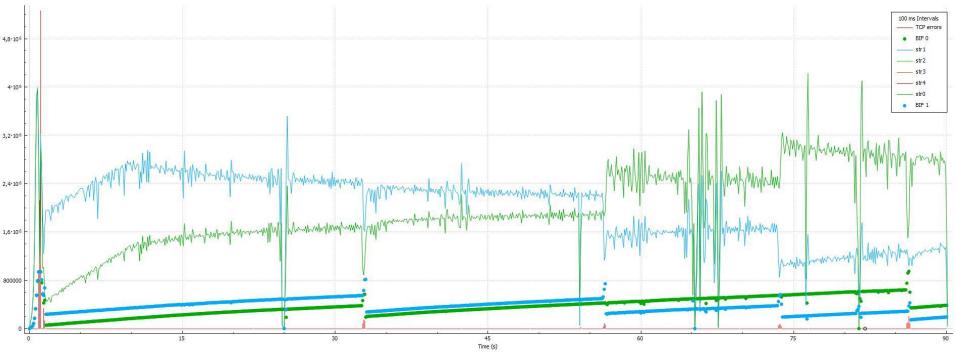




Collateral damage – same as Reno. Good for lossy links. With 1% loss beats CUBIC with x5 factor.



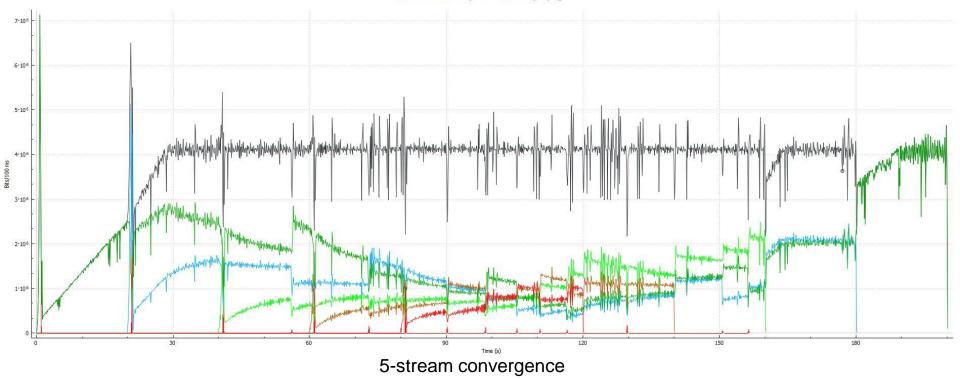
Wireshark IO Graphs: westwood.pcapng



vs. Reno Friendliness

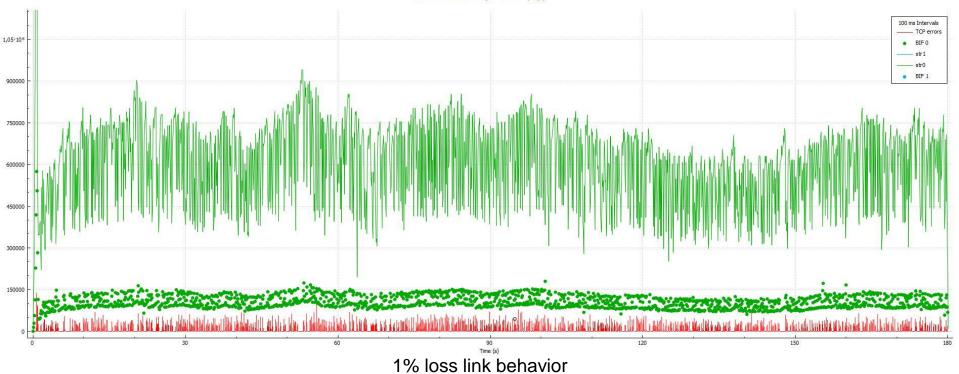


Wireshark IO Graphs: westwood.pcapng





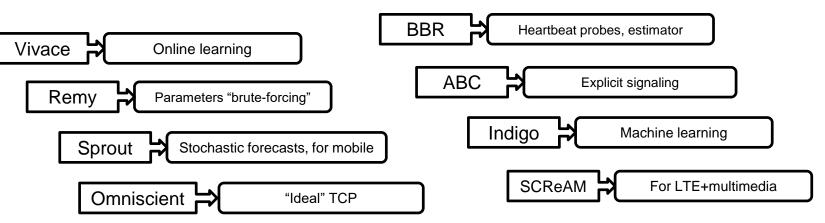
Wireshark IO Graphs: eth0 (tcp)



## The future?



- Multiple signals (ACK inter-arrival time, timestamps, delay with minimal RTT value tracking, packet loss).
- Learning-based (the use of assumption model).
- No pure ACK clocking (switch to combination of ACK clocking + pacing model). *cnwd* + *time gap* from last sent packet.
- Integrating into other protocols (PCC, QUIC on top of UDP).
- Pushing CA into user-space + using API (concept, Linux).
- Reinventing SlowStart (Flow-start, "Paced Chirping", now more for datacenter environment).





### Core ideas:

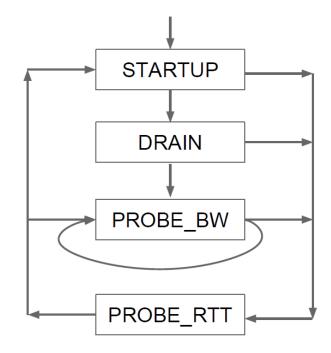
"Heartbeat"



- 1. RTT and Bottleneck BW estimation (*RTprop* and *BtlBw* variables) + active probing.
- 2. Uses periodic spike-looking active probes (+/- 25%) for Bottleneck BW testing.
- 3. Uses periodic pauses for "Base RTT" measuring.
- 4. Tracks App-limited condition (nothing to send) to prevent underestimation.
- 5. Doesn't use AIMD in any form or shape. Uses pacing instead. Can handle sending speeds from 715bps to 2,9Tbps.

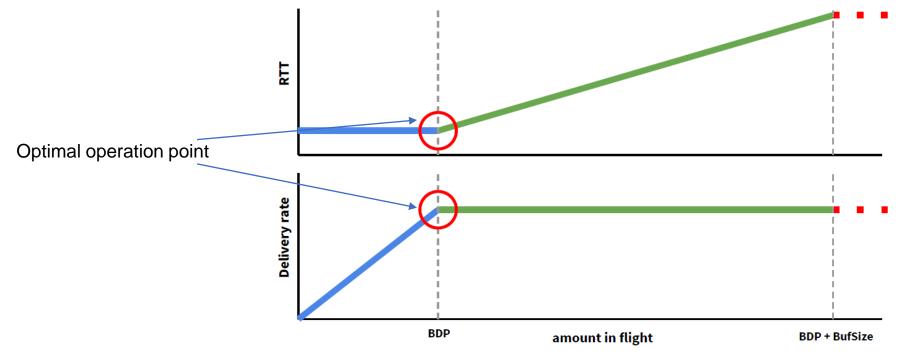
### cwnd control rules - 4 different phases:

- Startup (beginning of the connection)
- Drain (right after startup)
- Probe\_BW (most of the time)
- **Probe\_RTT** (periodically every 10 seconds)







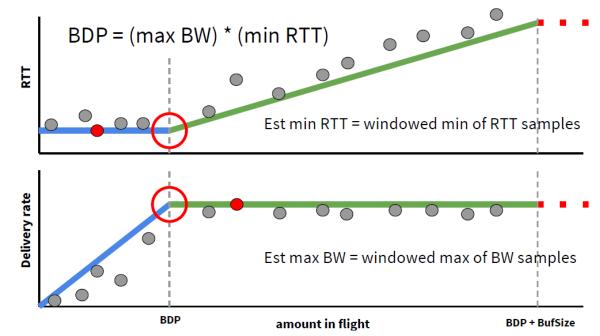


\* From "Making Linux TCP Fast". Yuchung Cheng. Neal Cardwell. Netdev 1.2 Tokyo, October, 2016"





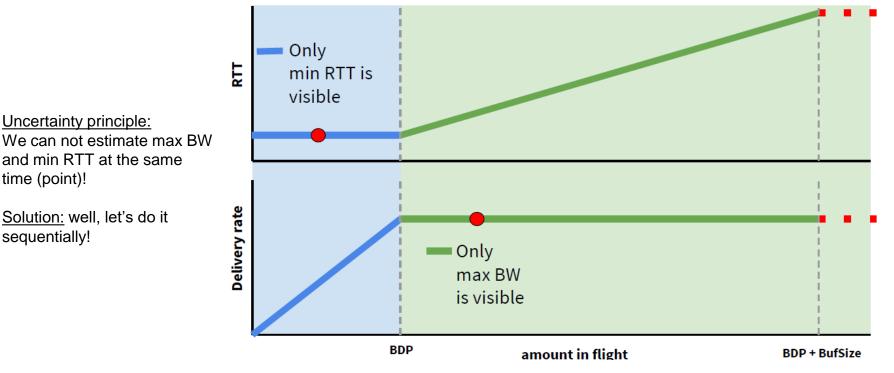
Estimating optimal point (max BW, min RTT)



\* From "Making Linux TCP Fast". Yuchung Cheng. Neal Cardwell. Netdev 1.2 Tokyo, October, 2016"







\* From "Making Linux TCP Fast". Yuchung Cheng. Neal Cardwell. Netdev 1.2 Tokyo, October, 2016"

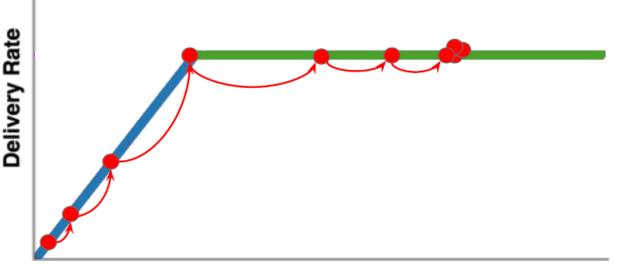






Startup phase: exponential probe for max BW.

Stopped if BW growth is less than 25% for 3 sequential probes.



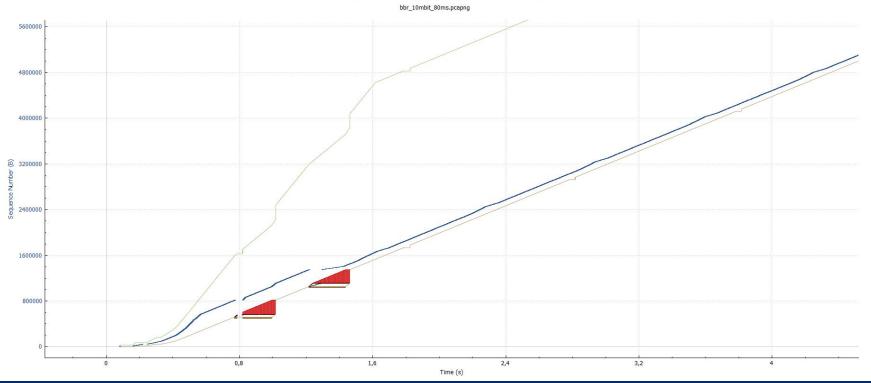
## Amount Inflight

\* From "Making Linux TCP Fast". Yuchung Cheng. Neal Cardwell. Netdev 1.2 Tokyo, October, 2016"





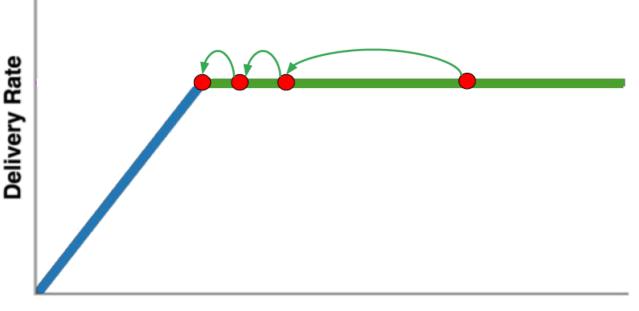
Sequence Numbers (tcptrace) for 10.10.10.10:34612  $\rightarrow$  10.10.10.12:51569







Drain phase: trying to get rid of queue formed during startup phase.



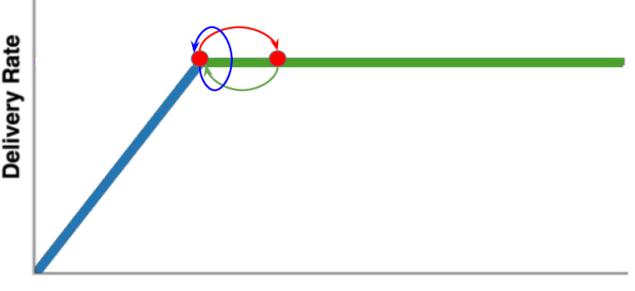
## Amount Inflight

\* From "Making Linux TCP Fast". Yuchung Cheng. Neal Cardwell. Netdev 1.2 Tokyo, October, 2016"





Probe BW phase: do spikes in sending rate (1,25 followed by 0.75 gains, each one of RTT length)



## Amount Inflight

\* From "Making Linux TCP Fast". Yuchung Cheng. Neal Cardwell. Netdev 1.2 Tokyo, October, 2016"

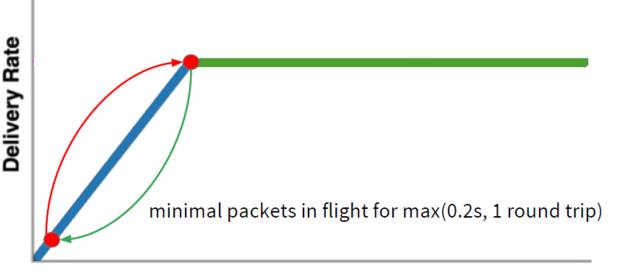






Probe RTT phase:

drop *cwnd* to 4 for 0,2 sec every 10 sec



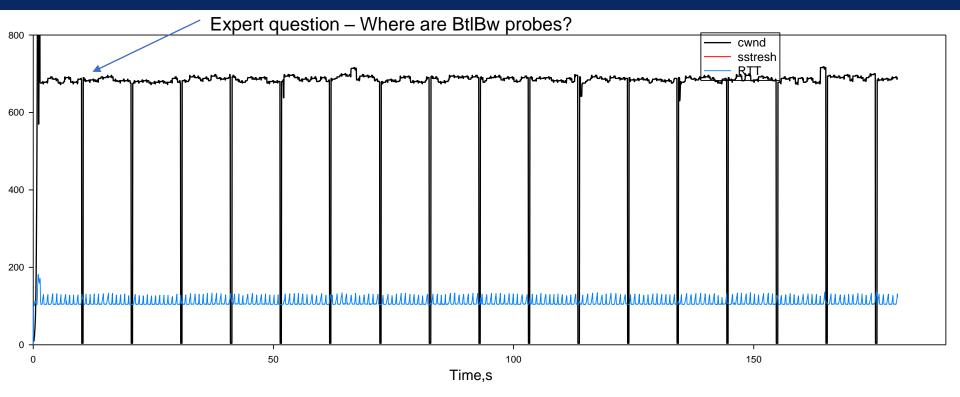
## Amount Inflight

[\*] if continuously sending

\* From "Making Linux TCP Fast". Yuchung Cheng. Neal Cardwell. Netdev 1.2 Tokyo, October, 2016"

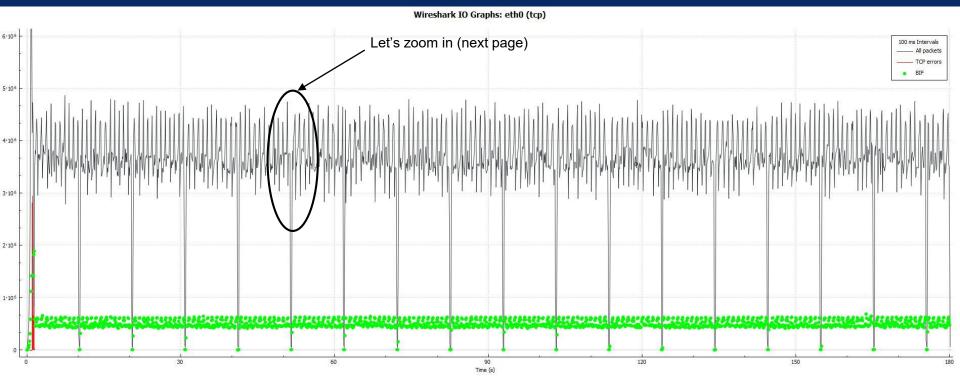








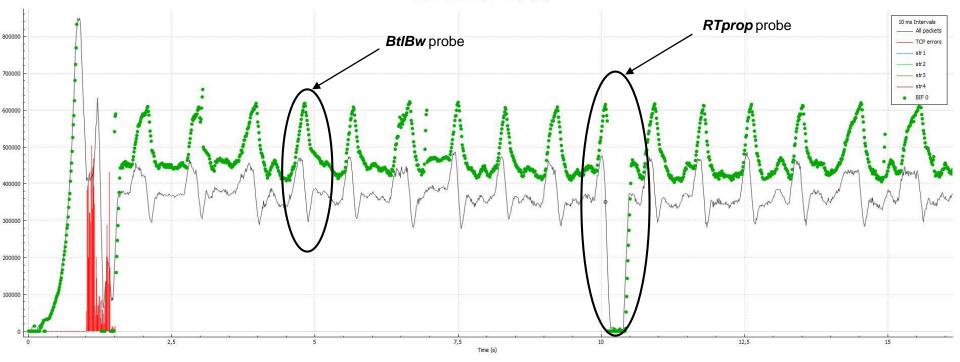








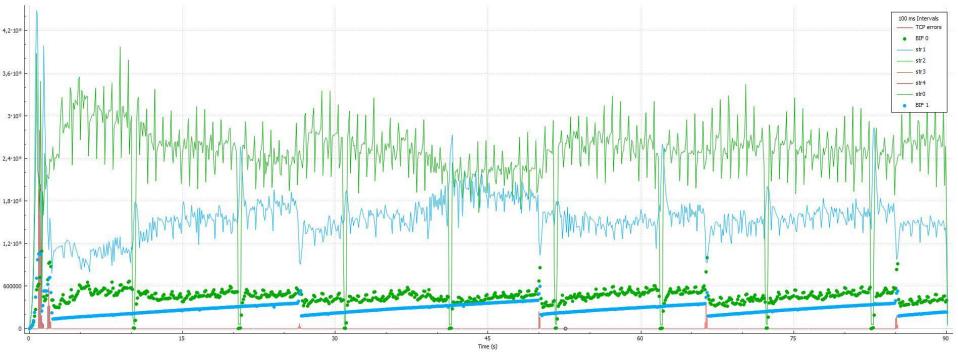
Wireshark IO Graphs: bbr.pcapng







Wireshark IO Graphs: bbr.pcapng

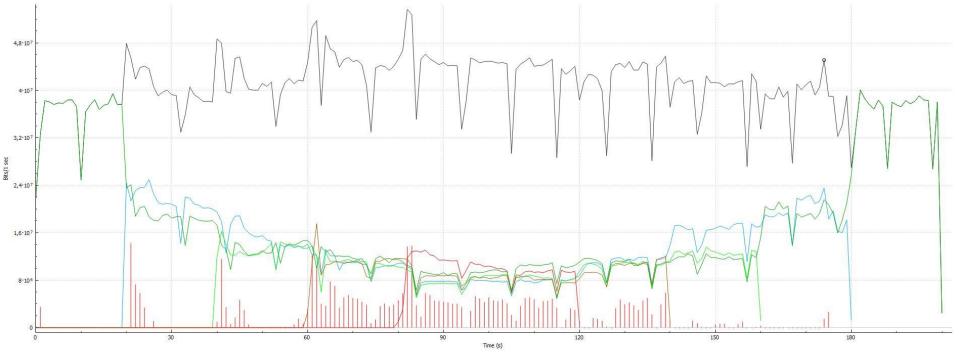


vs. Reno Friendliness





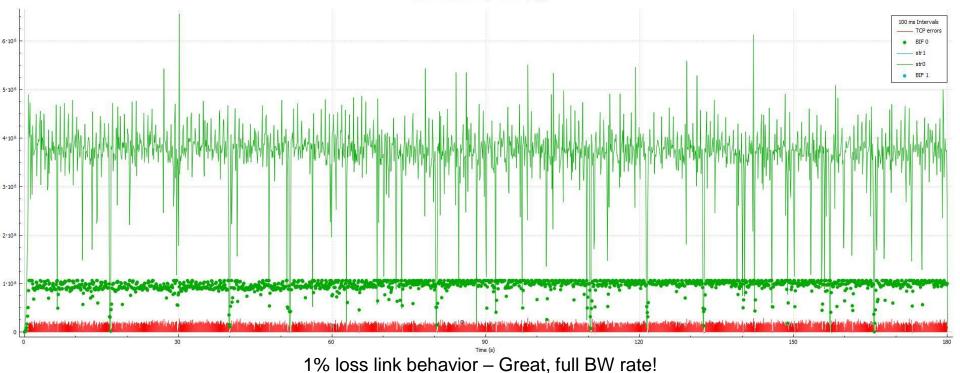
Wireshark IO Graphs: bbr.pcapng



5-stream convergence

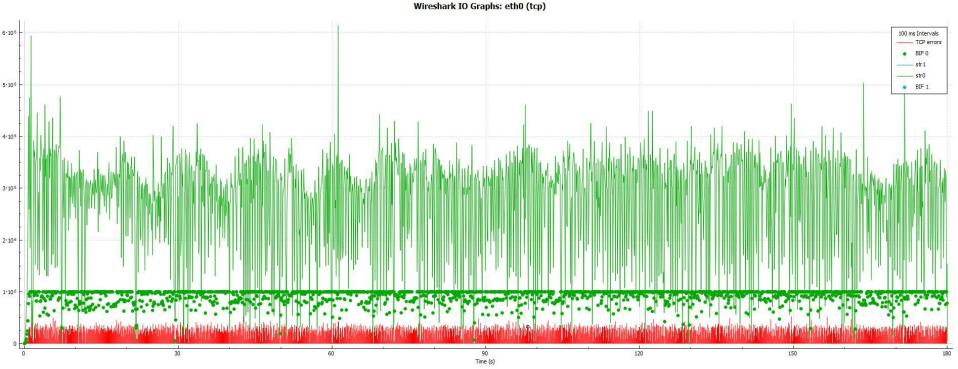












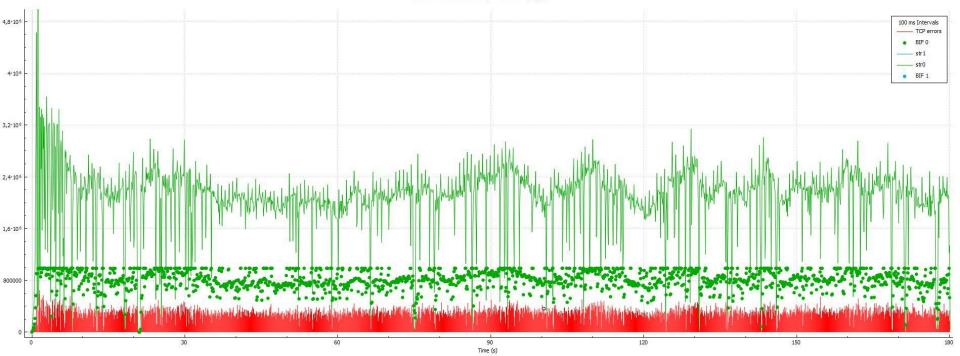
5% loss link behavior – 30Mbps out from 40, amazing!







Wireshark IO Graphs: eth0 (tcp)



10% loss link behavior – 24Mbit out of 40 – is it possible to kill it at all?

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Wireshark IO Graphs: eth0 (tcp)



20% loss link behavior – alright, we went too far <sup>(2)</sup>, but...



## Attacks on CA



### Three different types of attack are aimed to make a sender faster:

- 1. ACK division attack (intentional accelerating of CA algorithm)
- 2. DUP ACK spoofing (influencing on Fast Recovery phase)
- 3. Optimistic ACKing

# Used flowgrind commands



for cong in 'reno' 'scalable' 'http' 'bic' 'nv' 'cubic' 'vegas' 'hybla' 'westwood' 'veno' 'yeah' 'illinois' 'cdg' 'bbr' 'lp'; do flowgrind -H s=10.10.10.10/192.168.112.253,d=10.10.10.12/192.168.112.233 -i 0.005 -O s=TCP\_CONGESTION=\$cong -T s=60,d=0 | egrep  $^S > /home/vlad/csv_no_loss/{$cong}_60s_no_loss.csv;$ 

sleep 10 done

Regular 1-stream probe

for cong in 'reno' 'scalable' 'http' 'highspeed' 'bic' 'cubic' 'vegas' 'hybla' 'nv' 'westwood' 'veno' 'yeah' 'illinois' 'cdg' 'bbr' 'lp'; do flowgrind -n 5 -H s=10.10.10.10/192.168.112.253,d=10.10.10.12/192.168.112.233 -O s=TCP\_CONGESTION=\$cong -T s=90,d=0 | egrep  $^S > /home/vlad/{$cong}_90s_intra_fair.csv;$ 

sleep 30

done

5-stream intra-protocol fairness

for cong in 'reno' 'scalable' 'htcp' 'highspeed' 'bic' 'cubic' 'vegas' 'hybla' 'nv' 'westwood' 'veno' 'yeah' 'illinois' 'cdg' 'bbr' 'lp'; do flowgrind -n 2 -F 0 -H s=10.10.10.10/192.168.112.253,d=10.10.10.12/192.168.112.233 -O s=TCP\_CONGESTION=\$cong -T s=90,d=0 -F 1 -H s=10.10.10/192.168.112.253,d=10.10.10.12/192.168.112.233 -O s=TCP\_CONGESTION=reno -i 0.01 -T s=90,d=0 | egrep ^S > /home/vlad/{\$cong}\_90s\_reno\_friendl.csv;

sleep 30 done

### vs. Reno Friendliness

flowgrind -n 5 -F 0 -H s=10.10.10.10/192.168.112.253,d=10.10.10.12/192.168.112.233 -O s=TCP\_CONGESTION=\$cong -T s=100,d=0 -F 1 -H s=10.10.10/192.168.112.253,d=10.10.10.12/192.168.112.233 -O s=TCP\_CONGESTION=\$cong -Y s=10 -T s=80,d=0 -F 2 -H s=10.10.10.10/192.168.112.253,d=10.10.10.12/192.168.112.233 -O s=TCP\_CONGESTION=\$cong -Y s=20 -T s=60,d=0 -F 3 -H s=10.10.10.10/192.168.112.253,d=10.10.10.12/192.168.112.233 -O s=TCP\_CONGESTION=\$cong -Y s=30 -T s=40,d=0 -F 4 -H s=10.10.10.10/192.168.112.253,d=10.10.10.12/192.168.112.233 -O s=TCP\_CONGESTION=\$cong -Y s=40 -T s=20,d=0| egrep ^S > /home/vlad/{\$cong}\_100s\_5str\_converg.csv}







# Topic for next time? Network-assisted congestion control, state-of-the-art algorithms deep dive?

Thanks for your attention!